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(71) Applicant (for all designated States except US): **MO-TORIKO INC.**; Nerine Chambers, P.O. Box 905, Road Town, Tortola (VG).

(72) Inventors; and

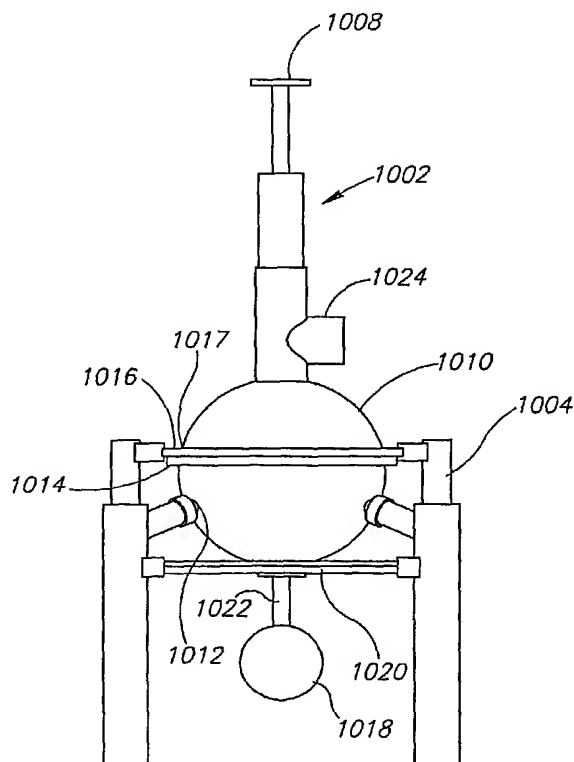
(75) Inventors/Applicants (for US only): **EINAV, Omer** [IL/IL]; 42875 Kfar Monash (IL). **EINAV, Haim** [IL/IL]; 28 Shlush Street, 65149 Tel-Aviv (IL). **ROUSSO, Benny**[IL/IL]; 12 Henry Bergson Street, 75801 Rishon Lezion (IL). **SHABANOV, Doron** [IL/IL]; 34 Hadkalim Boulevard, 44862 Zur Igal (IL). **KATZIR, Eran** [IL/IL]; 12 Amnon Vetamar Street, 48580 Rosh Ha'Ayin (IL). **BINYAMINI, Gad** [IL/IL]; 45870 Moshav Hagor (IL).(74) Agents: **FENSTER, Paul** et al.; FENSTER & COMPANY, INTELLECTUAL PROPERTY LTD., P.O. Box 10256, 49002 Petach Tikva (IL).

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(54) Title: METHODS AND APPARATUS FOR REHABILITATION AND TRAINING



(57) Abstract: The invention relates to a rehabilitation device which guides a patient to perform a motion with a correct spatial trajectory, by the device applying one or more pushing, assisting, reminding, responding and/or resisting forces during a motion (or intent to move) by the patient. The forces are applied by an actuator, for example, a robotic articulated arm or a spherically jointed lever. The applied forces act as a force fields, optionally continuous, which impeded and/or guides a patient. The device can be programmable with various trajectories (paths and/or velocities) and/or forces. The forces at one point in the trajectory can vary responsive to an actual trajectory by the patient and/or responsive to a rehabilitation plan and/or improvement of the patient. The device can learn a motion entered by a physiotherapist and replay it for the patient.



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